

11.0 User Programming Tricks



- Important concepts
- Useful overall strategies
- When to use various user program segments



User Program Files



- A user program file contains **one or more** program segments (functions).
- Each user program file is associated with **one and only one** potential array.
- Each potential array can be associated with **one and only one** user program file.
- User program files **share the name** of their array (e.g. **einzel.pa0 <> einzel.prg**).



Legal Program Segments

Only one segment of each type can be in a user program file

Define_Data

Defines Global variables and arrays

Init_P_Values

Pre-sets fast adjust potentials (new)

Initialize

Initializes ion's starting parameters

Tstep_Adjust

Controls time step size used

Fast_Adjust

Fast adjusts potentials as ions fly

Efield_Adjust

Adjusts electrostatic fields

Mfield_Adjust

Adjusts magnetic fields

Accel_Adjust

Adjusts ion accelerations

Other_Actions

Post tstep control of ion's parameters

Terminate

Post flight analysis and rerun control



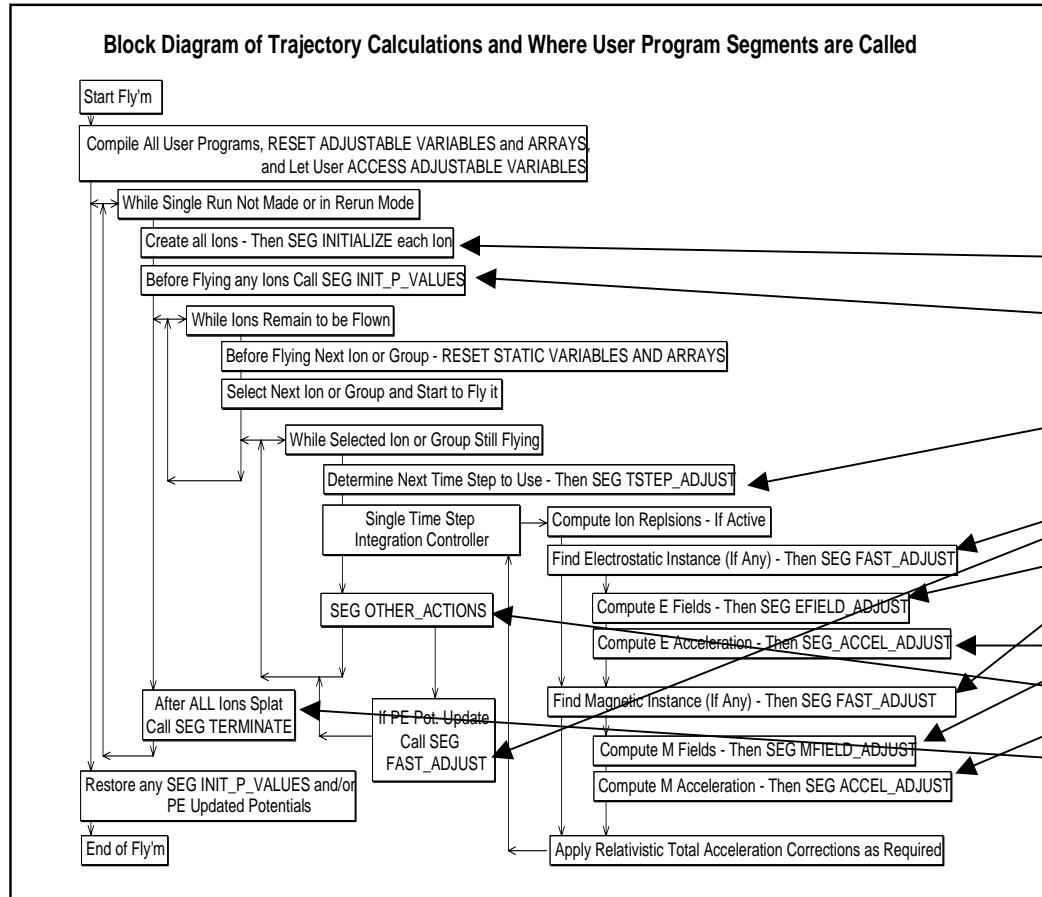
Program Segment Access Rules



- Each program segment is **ONLY** accessed at **specified points** in the trajectory computation cycle.
- The ion **MUST** be in an instance that **references** a potential array that **has** a user program file **containing** the program segment (e.g. Initialize). The **ONLY** exception is the Init P Values segment.



Program Segments and Calculations



Program Segments

Initialize
Init_P_Values
Tstep_Adjust
Fast_Adjust
Efield_Adjust
Mfield_Adjust
Accel_Adjust
Other_Actions
Terminate



Segment Access Paradigm



- Reserved Variables used for communication
- The **propose and modify** paradigm:
 - 1. SIMION calculates: proposed time step
 - 2. SIMION calls Tstep_Adjust (as per rules) passing value in ion_time_step
 - 3. Tstep_Adjust examines and/or modifies the value in ion_time_step
- Reserved Variable r/w access is controlled



Reserved Variables

- Reserved Variables used for communication between SIMION and program segments

Variable Name	Use	Units	Read Access	Write Access
Adj_Elect00 to Adj_Elect30	Fast Adj Electrode ¹ Voltages	Volts	Fast_Adjust Init_P_Values	Fast_Adjust Init_P_Values
Adj_Pole00 to Adj_Pole30	Fast Adj Pole ¹ Mag Potentials	Mags	Fast_Adjust Init_P_Values	Fast_Adjust Init_P_Values
Ion_Ax_mm Ion_Ay_mm Ion_Az_mm	Ion's current Acceleration (WB Orientation)	mm/micro sec ²	Accel_Adjust Other Actions Terminate	Accel_Adjust
Ion_BfieldX_gu Ion_BfieldY_gu Ion_BfieldZ_gu	Magnetic Field at Ion's Location (PA's Orientation)	Gauss	Mfield_Adjust	Mfield_Adjust
Ion_BfieldX_mm Ion_BfieldY_mm Ion_BfieldZ_mm	Magnetic Field at Ion's Location (WB Orientation)	Gauss	Accel_Adjust Other Actions Terminate	None
Ion_Charge	Ion's current charge	in units of elementary charge	Any Prog Seg except Init_P_Values	Initialize Other Actions
Ion_Color	Color of Ion	0-15	Initialize Other Actions	Initialize Other Actions
Ion_DvoltageX_gu Ion_DvoltageY_gu Ion_DvoltageZ_gu	Voltage Gradient at Ion's Location (PA's Orientation)	Volts/grid unit	Efield_Adjust	Efield_Adjust
Ion_DvoltageX_mm Ion_DvoltageY_mm Ion_DvoltageZ_mm	Voltage Gradient at Ion's Location (WB Orientation)	Volts/mm	Mfield_Adjust Accel_Adjust Other Actions Terminate	None
Ion_Instance	Current Instance	1- max instance	Any Prog Seg except Init_P_Values	None
Ion_Mass	Ion's current mass	amu	Any Prog Seg except Init_P_Values	Initialize Other Actions
Ion_mm_Per_Grid_Unit	Min Current Scaling ²	mm/grid unit	Any Prog Seg except Init_P_Values	None
Ion_Number	Ion's Number	1- max ion	Any Prog Seg except Init_P_Values	None

Variable Name	Use	Units	Read Access	Write Access
Ion_Px_Abs_gu Ion_Py_Abs_gu Ion_Pz_Abs_gu	Ion's current PA Array Coordinates	grid units (PA's Abs Coordinates)	Any Prog Seg except Init_P_Values	None
Ion_Px_gu Ion_Py_gu Ion_Pz_gu	Ion's current (PA's Coordinates)	grid units (PA's Coordinates)	Any Prog Seg except Init_P_Values	None
Ion_Px_mm Ion_Py_mm Ion_Pz_mm	Ion's current Workbench Coordinates	mm (WB Coordinates)	Any Prog Seg except Init_P_Values	Initialize Other Actions
Ion_Splat	Ion Status Flag ³	Flying = 0 Not Flying != 0	Initialize Other Actions	Initialize Other Actions
Ion_Time_of_Birth	Ion's Birth Time	micro seconds	Any Prog Seg except Init_P_Values	Initialize Other Actions
Ion_Time_of_Flight	Ion's current TOF ⁴	micro seconds	Any Prog Seg except Init_P_Values	Other Actions
Ion_Time_Step	Ion's Time Step ⁵	micro seconds	All but Initialize and Init_P_Values	Tstep_Adjust
Ion_Volts	Electrostatic Pot at Ion's Location	Volts	Efield_Adjust Mfield_Adjust Accel_Adjust Other Actions Terminate	Efield_Adjust
Ion_Vx_mm Ion_Vy_mm Ion_Vz_mm	Ion's current Velocity (WB Orientation)	mm/micro sec	Any Prog Seg except Init_P_Values	Initialize Other Actions
Rerun_Flym	Rerun Flym Flag ⁶	NO = 0 YES = 1	Initialize Other Actions Terminate	Initialize Other Actions Terminate
Trajectory_Image_Control	Controls Trajectory Image Viewing and Recording ⁷	Value View Retain 0 YES YES 1 YES NO 2 NO YES 3 NO NO	Initialize Other Actions Terminate	Initialize Other Actions Terminate
Retain_Changed_Potentials	Controls restoring of changed potentials at end of Fly'm'	NO = 0 (default) YES = 1	None	Terminate
Update_PE_Surface	New PE Surface ⁸	YES != 0	None	Other Actions



Temporary Variables



- Visibility: Visible **only** in user program segment that defines it
- Lifetime: Exists **only** during a reference to the program segment
- User Adjustability: **No**
- Conserves Changes: **No**
- Error Trapping: **Yes** (**for sto without rcl**)



Static Variables & Arrays



- Visibility: Globally visible to **most** user programs except: **Initialize**, **Init_P_values**, and **Terminate**.
- Lifetime: Reset **before** each ion or group flight.
- User Adjustability: **No**
- Conserves Changes: **No**



Adjustable Variables & Arrays



- Visibility: Globally visible to **all** user programs
- Lifetime: Values conserved throughout **entire** fly'm (**including reruns**).
- User Adjustable:
 - **Before** ion flying starts
 - **During** ion flying (via **AdjV** tabbed screen)
- Conserves Changes: **YES** (**before fly'm**)



Controlling Variable Visibility

File	ON	All	E Fmt	As Defined	Sorted Adjustable
Single run if one	+	.,.	,0.000000		
Bx_Gauss	+	.,.	,0.000000		
Primary Beam Charging	+	.,.	,0.000000		
left_voltage	+	.,.	,10.000000		
right_voltage	+	.,.	,10.000000		
Convergence_Objective	+	.,.	,2.000000		
step_limit	+	.,.	,1.000.0000		
target_voltage	+	.,.	,0.000000		
use_defined_max_min_if_one	+	.,.	,0.000000		
starting_max_voltage	+	.,.	,100.000000		
starting_min_voltage	+	.,.	,100.000000		
max_voltage	+	.,.	,100.000000		
min_voltage	+	.,.	,100.000000		
use_special_pos_if_one	+	.,.	,0.000000		
Cone_Angle_Off_Vel_Axis	+	.,.	,89.000000		
Random_Offset_mm	+	.,.	,6.000000		
n_extracted	+	.,.	,0.000000		
net_charge	+	.,.	,0.000000		
p_count	+	.,.	,0.000000		
n_count	+	.,.	,0.000000		
e_count	+	.,.	,0.000000		
p_charge	+	.,.	,0.000000		
n_charge	+	.,.	,0.000000		
e_charge	+	.,.	,0.000000		
first_flym	+	.,.	,0.000000		
first_ion	+	.,.	,0.000000		
finished	+	.,.	,0.000000		
ke_m_025	+	.,.	,0.000000		
ke_m_05	+	.,.	,0.000000		

All
Adjustable
Variables

File	ON	OK	E Fmt	As Defined	Sorted Adjustable
Bx_Gauss	+	.,.	,0.000000		
Primary_Beam_Charging	+	.,.	,0.000000		
Convergence_Objective	+	.,.	,2.000000		
Cone_Angle_Off_Vel_Axis	+	.,.	,89.000000		
Random_Offset_mm	+	.,.	,6.000000		

_OK
Leading
Underscore
Adjustable
Variables

AdjV runtime Screen

Normal	PAs	WrkBnch	Contour	ZZZ	AdjV

- Adjustable Variables
 - Use leading underscore in names to see (e.g. _Left_Electrode_Voltage)



Controlling Variable Visibility

- Use Adjustable & Static Arrays for Flags

Adefa aflags 20 ;"defaults.dat" adjustable flags -- initialized
Adefs sflag 500 ; static array flag -- zeroed for each ion

1 arcl aflags ; simple recall (`x = aflags[1]`)
0 1 sto aflags ; simple store (`aflags[1] = 0`)

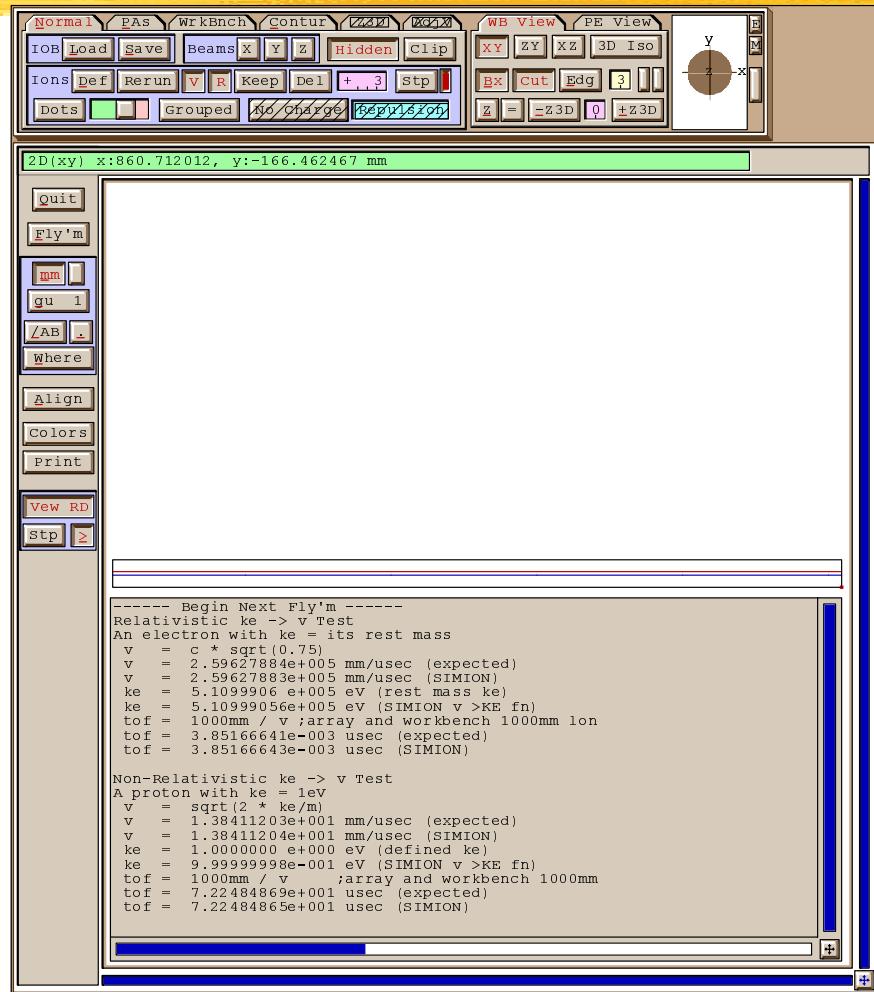
defa flag 0 ;flag shown at start (**unless _OK underscore**)

rcl flag
1 sto flag



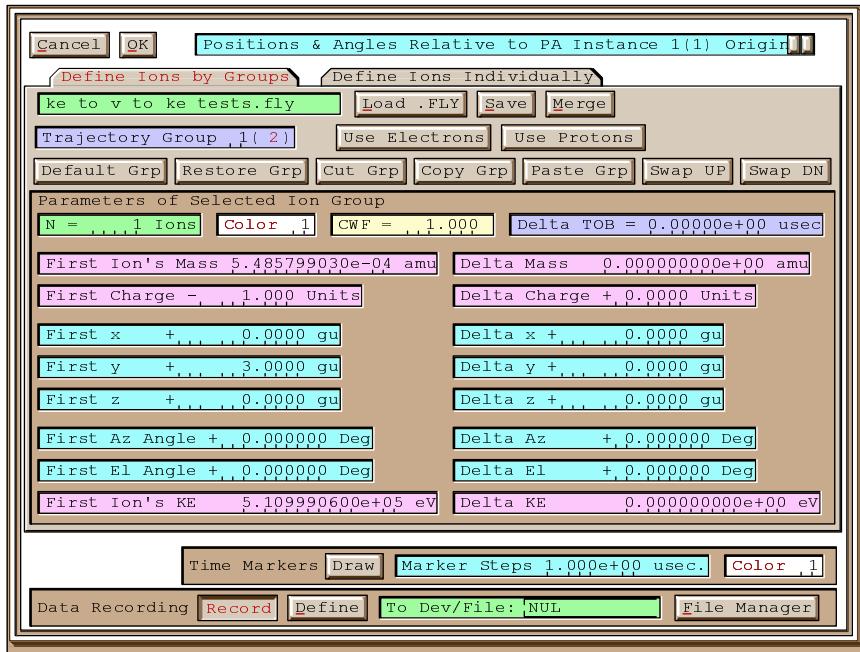
Creating Integrated Demos

1. Ke to Velocity (Test Demo)



Creating Integrated Demos

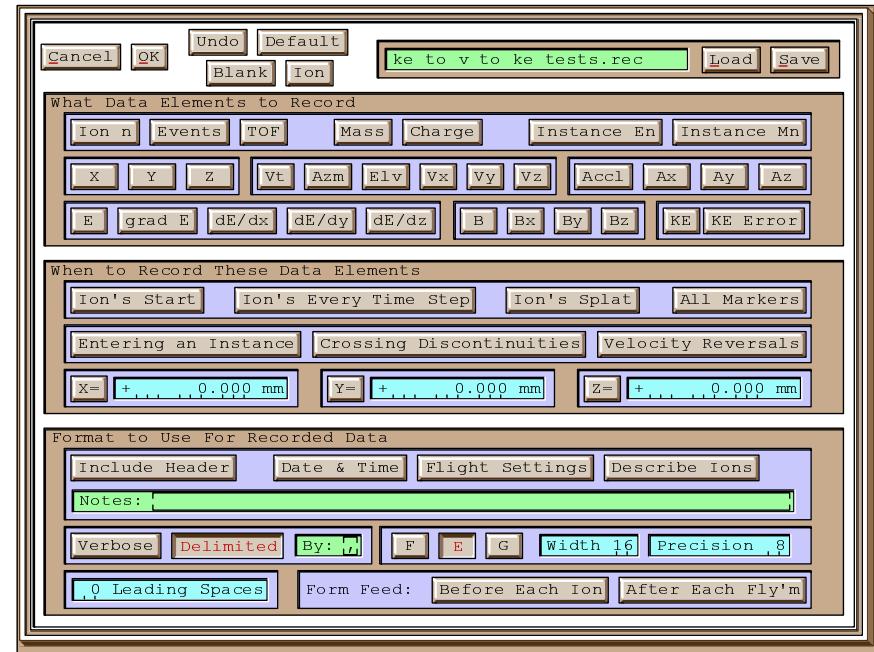
1. Ke to Velocity (Test Demo)



Ion Definitions



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Data Recording

Creating Integrated Demos

1. Ke to Velocity (Test Demo)

```
seg other_actions

rcl ion_splat x=0 exit
1 rcl ion_mass x>y goto ions ;jump if proton
                                ;exit if ion hasn't splatted
                                ;else output relativistic electron data
message ;Relativistic ke -> v Test
message ;An electron with ke = its rest mass
                                ;relativistic velocity from
                                ;2 = 1/(sqrt(1 - v*v/c*c))
message ; v = c * sqrt(0.75)
                                ; given c = 2.99792458e+005 mm/usec
message ; v = 2.59627884e+005 mm/usec (expected)
rcl ion_vx_mm
                                ; velocity at splat
message ; v = # mm/usec (SIMION)
                                ; rest mass of electron
                                ; and starting ke
message ; ke = 5.1099906 e+005 eV (rest mass ke)
rcl ion_mass
rcl ion_vx_mm
>ke
                                ; get mass of electron
                                ; get its exit velocity
                                ; convert back to ke as check
message ; ke = # eV (SIMION v >KE fn)
                                ;equation for const velocity tof
message ; tof = 1000mm / v ;array and workbench 1000mm long
                                ;tof assuming expected velocity
message ; tof = 3.85166641e-003 usec (expected)
rcl ion_time_of_flight
                                ;tof computed by SIMION
message ; tof = # usec (SIMION)
message ;
exit

lbl ions
                                ;proton data output
message ;Non-Relativistic ke -> v Test
message ;A proton with ke = 1eV
message ; v = sqrt(2 * ke/m)
                                ; v = sqrt(2.0 * 1.60217733e-19/1.6726231e-27)
                                ;where 1eV = 1.60217733e-19 J
                                ; proton's mass = 1.6726231e-27 kg
message ; v = 1.38411203e+001 mm/usec (expected)
rcl ion_vx_mm
                                ; velocity at splat
message ; v = # mm/usec (SIMION)
                                ; defined initial ke
message ; ke = 1.0000000 e+000 eV (defined ke)
rcl ion_mass
                                ; get mass of proton
rcl ion_vx_mm
                                ; get its exit velocity
>ke
                                ; convert back to ke as check
message ; ke = # eV (SIMION v >KE fn)
                                ;equation for const velocity tof
message ; tof = 1000mm / v ;array and workbench 1000mm long
                                ;tof assuming expected velocity
message ; tof = 7.22484869e+001 usec (expected)
rcl ion_time_of_flight
                                ;tof computed by SIMION
message ; tof = # usec (SIMION)
exit
```



Creating Integrated Demos



- Recommended Strategies
 - Use auto-loading FLY (or ION) and REC files
 - Control displayed number format with REC file
 - Use self-evident message output if possible via Initialize, Other_Actions, Terminate, and/or data recording (REC)
 - Hide Adjustable Variables from user (e.g. **_Voltage (shown)**, **flag (hidden)**, or **via arrays**)



Randomizing Ions

- Use Initialize Segment to Randomize Ions

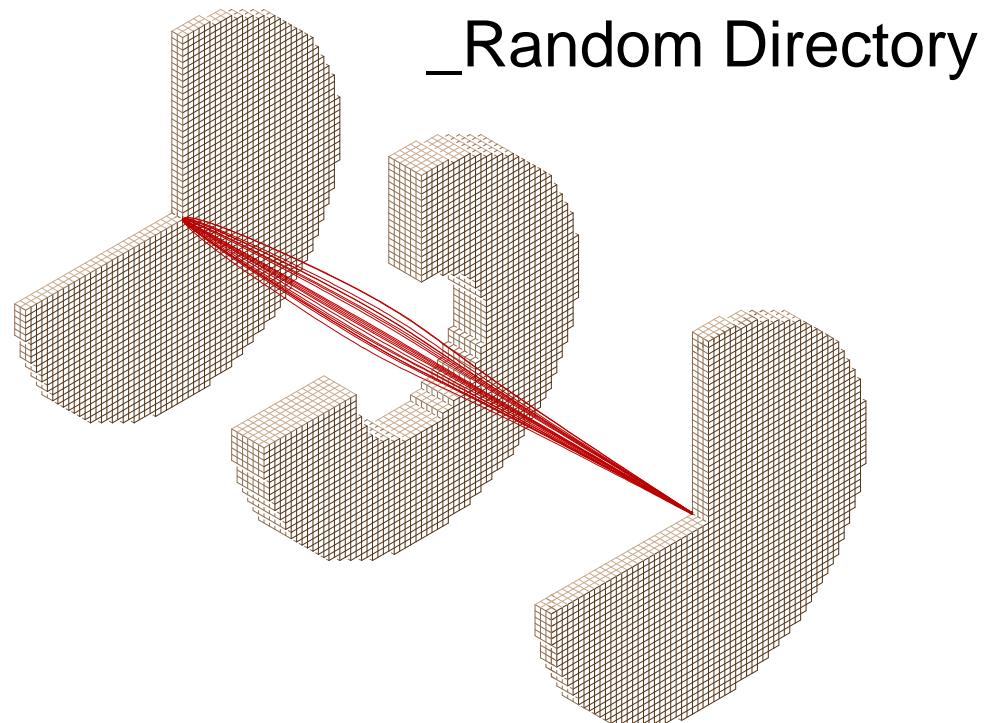
Initialize

Input Ions

Group of ions with identical starting parameters.

Adjustable Variables

Percent_Energy_Variation
Cone_Angle_Off_Vel_Axis



Randomizing Ions

• Initialize Segment Strategy

Get polar v components	Get ion's velocity components from SIMION Convert to 3D polar and save speed plus az and el angles
Compute KE Randomize KE Convert to v	get ion_mass, recall speed, convert to ke, and save ke use rand and percent_energy_variation to randomize ke get ion_mass, recall new ke, convert to v, and save speed
Create random conical pattern in vertical Convert to 3D Rectangular Swing back to az = el = 0	assume ion flying vertical randomize el off vertical by cone angle randomize az to +- 180 degrees convert to rectangular 3D coords rotate vector -90 in elevation (restores a starting point)
Rotate entry el Rotate entry az Pass V Rect. to SIMION	rotate vector initial el angle rotate vector initial az angle pass ion's velocity components back to SIMION



Initialize for Random Ions

```

;-----  

; this user program randomly changes the initial ke and direction of ions  

; energy is randomly changed +- Percent_Energy_Variation * ke  

; ions are emitted randomly within a cone of revolution around the  

; ion's defined velocity direction axis  

; the full angle of the cone is +- Cone_Angle_Off_Vel_Axis  

; (e.g. 90.0 is full hemisphere, 180 is a full sphere)  

;  

;----- you can use it with your own lenses without modification -----  

; (just rename user program file using your pa's name)  

;----- Note: you can also modify the emission distributions as desired -----  

defa Percent_Energy_Variation 50 ; (+- 50%) random energy variation  

defa Cone_Angle_Off_Vel_Axis 90 ; (+- 90 deg) cone angle hemisphere

seg initialize           ; initialize ion's velocity and direction
;----- get ion's initial velocity components -----
rcl ion_vz_mm           ; get ion's specified velocity components
rcl ion_vy_mm
rcl ion_vx_mm

;----- convert to 3d polar coords -----
>p3d                   ; convert to polar 3d

;----- save polar coord values -----
sto speed rlup          ; store ion's speed
sto az_angle rlup       ; store ion's az angle
sto el_angle             ; store ion's el angle

;----- make sure Percent_Energy_Variation is legal -----
; force 0 <= Percent_Energy_Variation <= 100
rcl Percent_Energy_Variation abs
100 x>rlup sto Percent_Energy_Variation

;----- make sure Cone_Angle_Off_Vel_Axis is legal -----
; force 0 <= Cone_Angle_Off_Vel_Axis <= 180
rcl Cone_Angle_Off_Vel_Axis abs
180 x>rlup sto Cone_Angle_Off_Vel_Axis

;----- calculate ion's defined ke -----
rcl ion_mass             ; get ion's mass
rcl speed                ; recall its total speed
>ke                     ; convert speed to kinetic energy
sto kinetic_energy        ; save ion's defined kinetic energy

;----- compute new randomized ke -----
; convert from percent to fraction
rcl Percent_Energy_Variation 100 /
sto del_energy 2 * rand * ; fac = 2 * del_energy * rand
rcl del_energy - 1 +      ; fac += 1 - del_energy
rcl kinetic_energy *      ; new ke = fac * ke

;----- convert new ke to new speed -----
rcl ion_mass              ; recall ion mass
x><y                  ; swap x any y
>spd                   ; convert to speed
sto speed                ; save new speed

;----- compute randomized el angle change 90 +- Cone_Angle_Off_Vel_Axis -----
;----- we assume elevation of 90 degrees for mean -----
;----- so cone can be generated via rotating az +- 90 -----
; (2 * Cone_Angle_Off_Vel_Axis * rand)
2 rcl Cone_Angle_Off_Vel_Axis * rand *
; - Cone_Angle_Off_Vel_Axis + 90
rcl Cone_Angle_Off_Vel_Axis - 90 +

;----- compute randomized az angle change -----
;----- this gives 360 effective because of +- elevation angels ---
180 rand * 90 -          ;      +- 90 randomized az

;----- recall new ion speed -----
rcl speed                ; recall new speed

;----- at this point x = speed, y = az, z = el -----
;----- convert to rectangular velocity components -----
>r3d                   ; convert polar 3d to rect 3d

;----- el rotate back to from 90 vertical -----
-90 >elr

;----- el rotate back to starting elevation -----
rcl el_angle >elr

;----- az rotate back to starting azimuth -----
rcl az_angle >azr

;----- update ion's velocity components with new values -----
sto ion_vx_mm            ; return vx
rlup
sto ion_vy_mm            ; return vy
rlup
sto ion_vz_mm            ; return vz
rlup

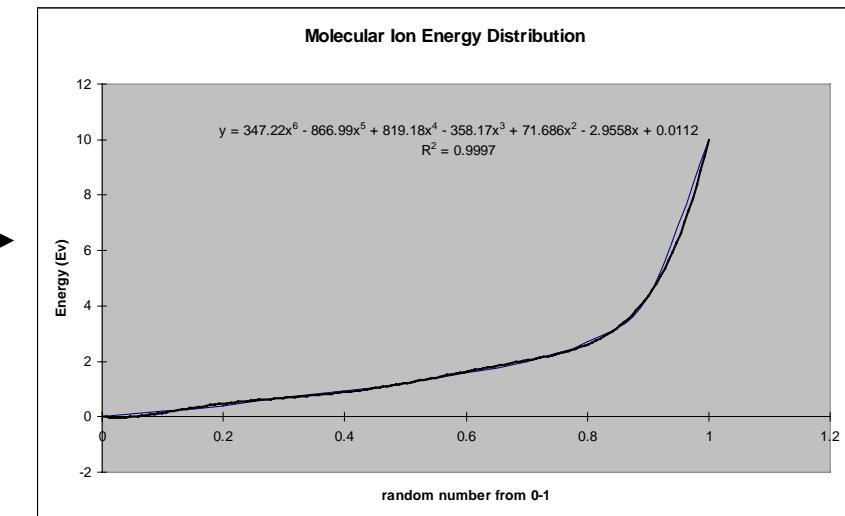
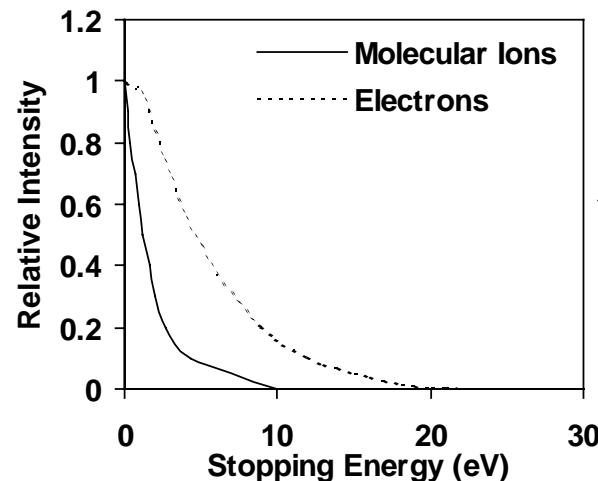
;----- done -----

```



Another Randomizing Example

- Monte Carlo example
 - Secondary ion energies (fitting)



Another Randomizing Example

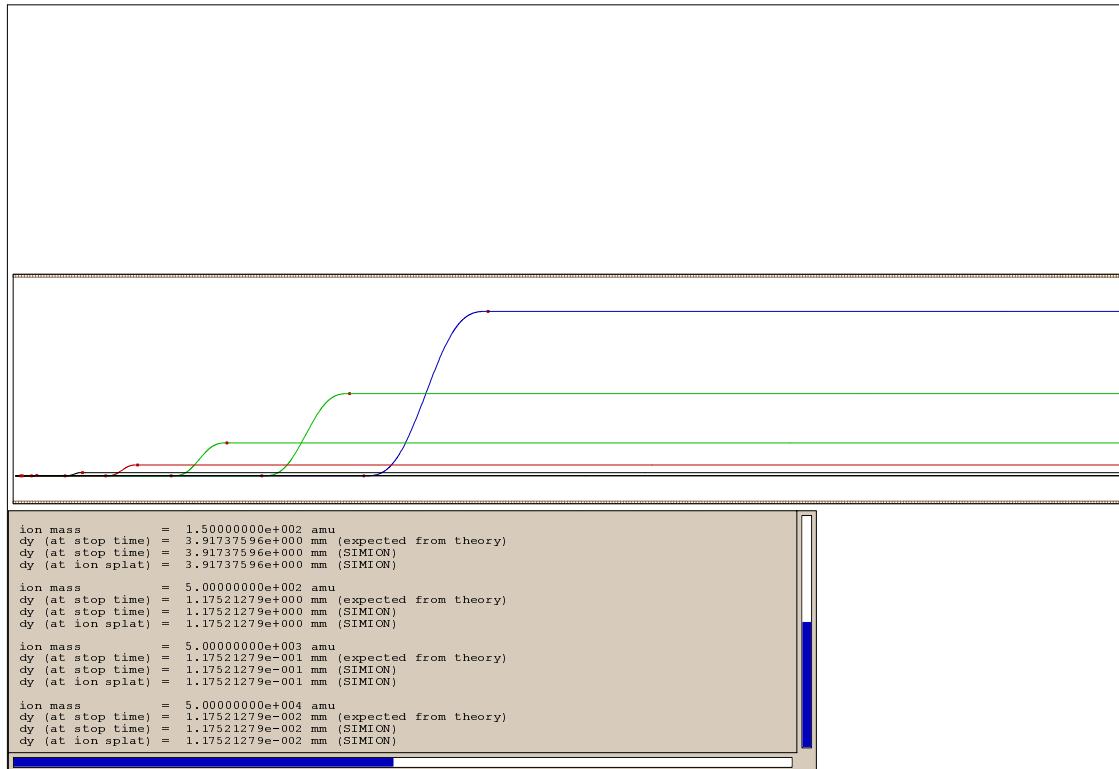
- Monte Carlo example cont.
 - Secondary ion energies (coding)

```
;molecular energies
rand sto x
    ;get random number x (0-1)
0.0112
    ; +0.0112
2.9558 rcl x * -          ; -2.9558x
71.686 rcl x      rcl x * sto xpower * + ; +71.686x^2
358.17 rcl xpower rcl x * sto xpower * - ; -358.17x^3
819.18 rcl xpower rcl x * sto xpower * + ; +819.18x^4
866.99 rcl xpower rcl x * sto xpower * - ; -866.99x^5
347.22 rcl xpower rcl x * sto xpower * + ; +347.22x^6
abs
```



Controlling Times and Time Steps

- Critical Timing Example



Controlling Times and Time Steps



- Strategy: Tstep_Adjust via Ion_Time_Step

If TOF \geq left then right test

If TOF + TS < left then exit

ion_time_step = left - TOF

exit

LBL right test

If TOF \geq right then exit

If TS > MAX then TS = MAX

If TOF + TS < right then exit

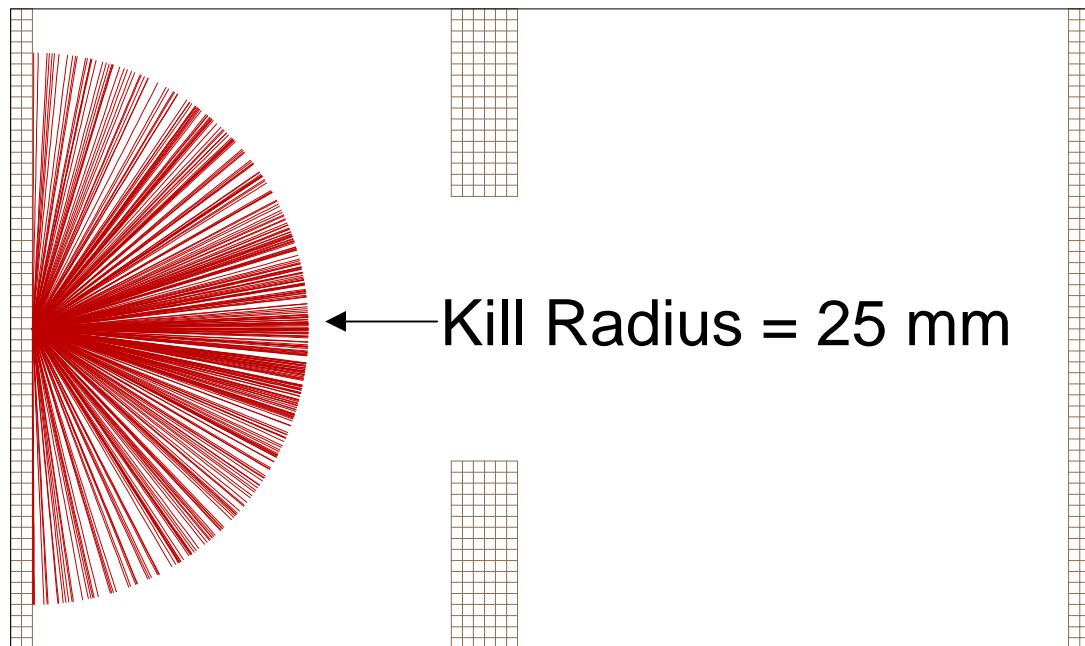
ion_time_step = right - TOF

exit



Binary Boundary Approach

- Use Tstep_Adjust and Other Actions



Binary Boundary Approach

- Strategy

Other_Actions Control

```
If boundary crossed
    if not too close
        restore prior ion state
        save time_step
        set half step flag
    else
        save ion's state
        (Px,Py,Pz,
         Vx,Vy,Vz,TOF)
```

Tstep Control

```
If half step flag not set
    exit
else
    get saved time_step
    halve it
    save to ion_time_step
    clear half step flag
```



Fast Adjusting Potentials



- Strategy: Fast_Adjust or Init_P_Values
 - Time varying fields: Fast_Adjust (only)
 - Tstep_Adjust may be needed for step size control
 - Static fields: Fast_Adjust or Init_P_Values
 - Fast_Adjust for large arrays and smaller numbers of ions.
 - Init_P_Values for smaller arrays and larger numbers of ions.
 - Conduct time trials (very useful).



Specifying Known Fields



- Strategy: Mfield_Adjust or Efield_Adjust
 - Fixed Magnetic fields (Mfield_Adjust)
 - Use field-free magnetic array
 - | | |
|-------------------|------------------------|
| 0 sto BfieldZ_gu | ;zero Bz |
| sto BfieldY_gu | ;zero By |
| rcl _Bfield_gauss | ;get Bx from Adj. Var. |
| sto BfieldX_gu | ;save user defined Bx |



Specifying Known Fields



- Strategy: Mfield_Adjust or Efield_Adjust
 - Measured Magnetic fields (Mfield_Adjust)
 - Use field-free magnetic array
 - Adefa Bfield 10000 ;"mfield.dat" measured B
 - Get ion's gu coords (abs or 3D)
Use to get interpolated B fields at point
Pass Bx, By, and Bz fields back to SIMION
(see measured magnetic fields example)



Specifying Known Fields

- Strategy: Mfield_Adjust or Efield_Adjust
 - Analytic Electrostatic fields (Efield_Adjust)

Selectively use	seg efield_adjust 3 rcl ion_number x<=y exit	;quadrupolar field ;use refined field <= 3
Compute and store potential	rcl ion_px_mm entr * rcl ion_py_mm entr * - 10 / sto ion_volts rcl ion_px_mm 0.2 * rcl ion_mm_per_grid_unit * sto ion_dvoltsx_gu	; x^2 ; (x^2 - y^2) ; (x^2 - y^2)/10 ; volts/mm x gradient ; volts/gu x gradient ; pass to SIMION
Compute and store x gradient	rcl ion_py_mm -0.2 * rcl ion_mm_per_grid_unit * sto ion_dvoltsy_gu 0 sto ion_dvoltsz_gu	; volts/mm y gradient ; volts/gu y gradient ; pass to SIMION ; no field in z
Compute and store y gradient		
Zero z gradient	exit	



Modifying Ion Accelerations

- Strategy: Use Accel_Adjust

```
seg accel_adjust ; beginning of accel_adjust segment

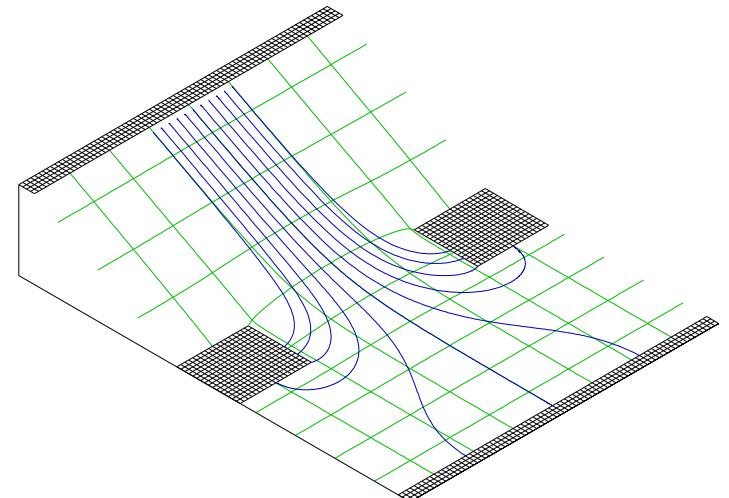
rcl ion_time_step x=0 exit ; exit if zero time step
rcl linear_damping x=0 exit ; exit if damping set to zero
abs sto damping ; force damping term to be positive
* sto tterm ; compute and save number of time constants
chs e^x 1><y - ; (1 - e^{-(t * damping)})
rcl tterm / sto factor ; factor = (1 - e^{-(t * damping)})/(t * damping)

rcl ion_ax_mm ; recall ax acceleration
rcl ion_vx_mm ; recall vx velocity
rcl damping * - ; multiply times damping and sub from ax
rcl factor * ; multiply times factor
sto ion_ax_mm ; store as new ax acceleration

rcl ion_ay_mm ; recall ay acceleration
rcl ion_vy_mm ; recall vy velocity
rcl damping * - ; multiply times damping and sub from ay
rcl factor * ; multiply times factor
sto ion_ay_mm ; store as new ay acceleration

rcl ion_az_mm ; recall az acceleration
rcl ion_vz_mm ; recall vz velocity
rcl damping * - ; multiply times damping and sub from az
rcl factor * ; multiply times factor
sto ion_az_mm ; store as new az acceleration
```

Drag Demo



Arbitrary Ion Accelerations



- Strategy: Use Accel_Adjust
 - Can define arbitrary field forces (e.g. $1/r^5$)
 - Can define arbitrary field directions
 - Always normal to ion's current velocity
 - Always parallel to ion's current velocity
 - Moving points of attraction
 - Random points of attraction
 - Whatever you can imagine



Controlling Ion's Fate



- Strategy: Other_Actions
 - Position
 - Velocity
 - Mass
 - Charge
 - Color
 - TOF
 - Splat
- User Programming's
Master Controller
(Most Powerful Program Segment)



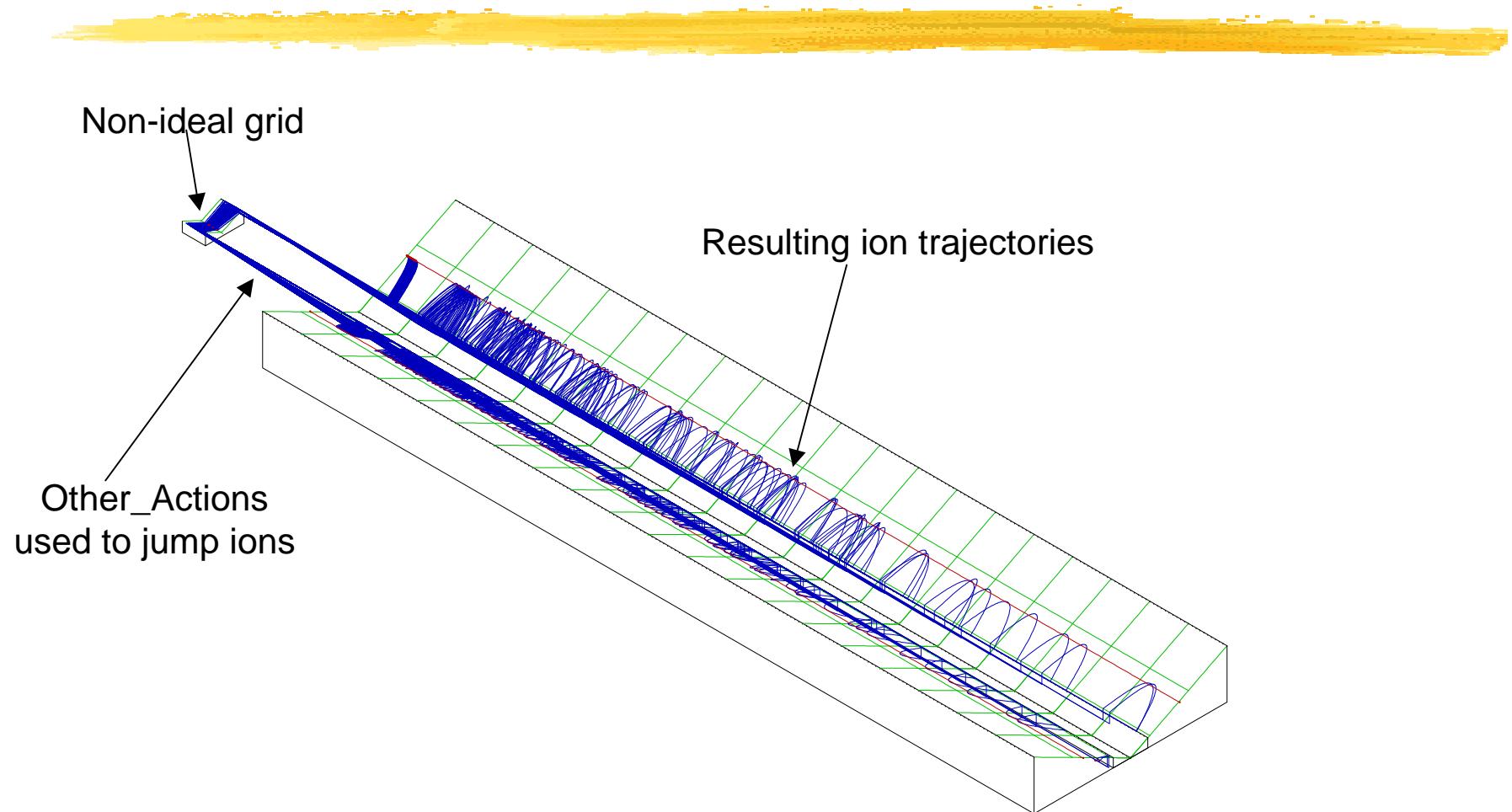
Controlling Ion's Fate



- Strategy: Other_Actions
 - Mass and/or charge
 - Energy and/or position
 - Boundary approaches
 - Collision simulations
 - Simulations involving jumps
 - Selective ion marking (e.g. via color & marks)
 - Selective ion killing

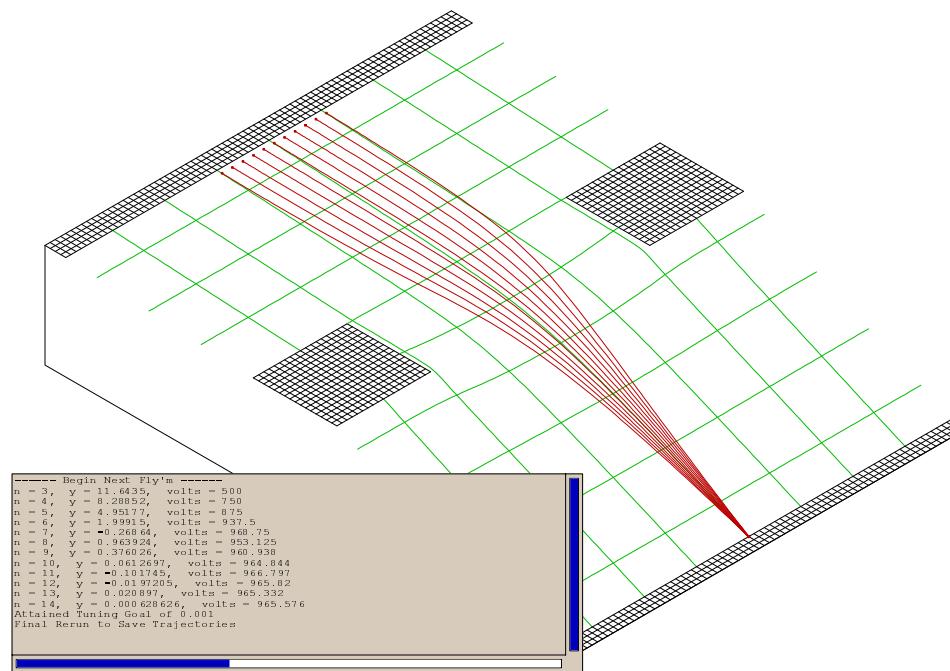


Controlling Ion's Fate



Controlling Successive Runs

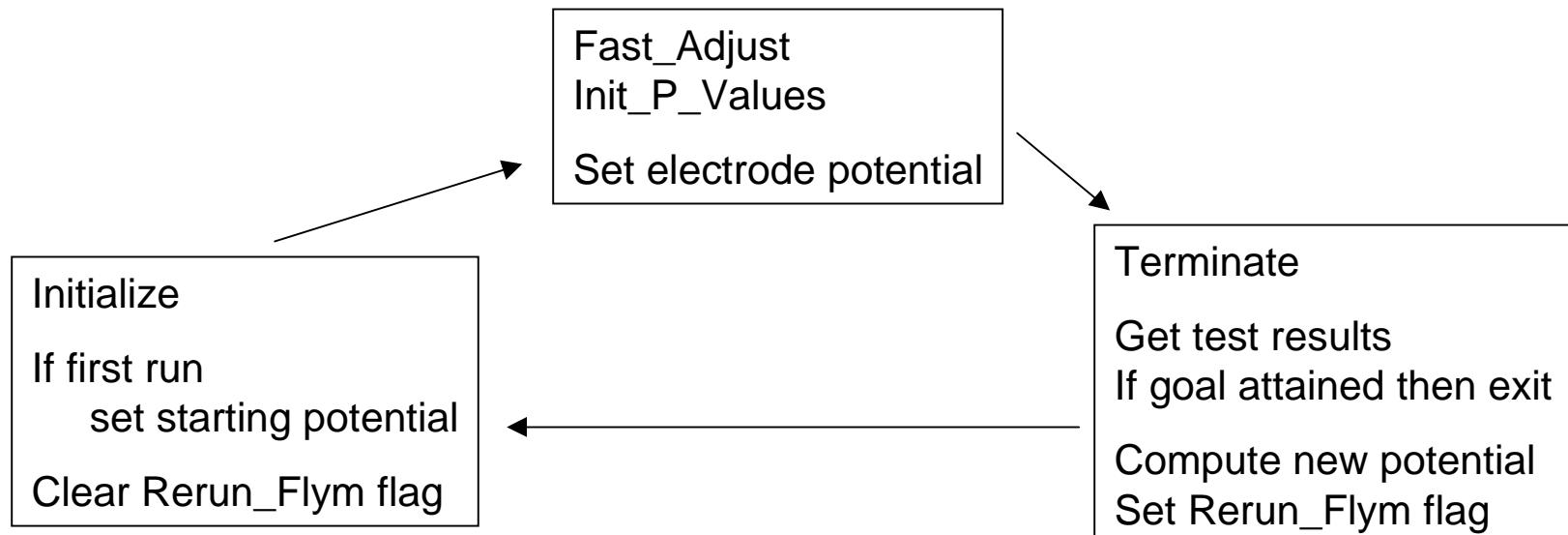
- Strategy: Terminate and Initialize
 - Via the Rerun_Flym reserved variable



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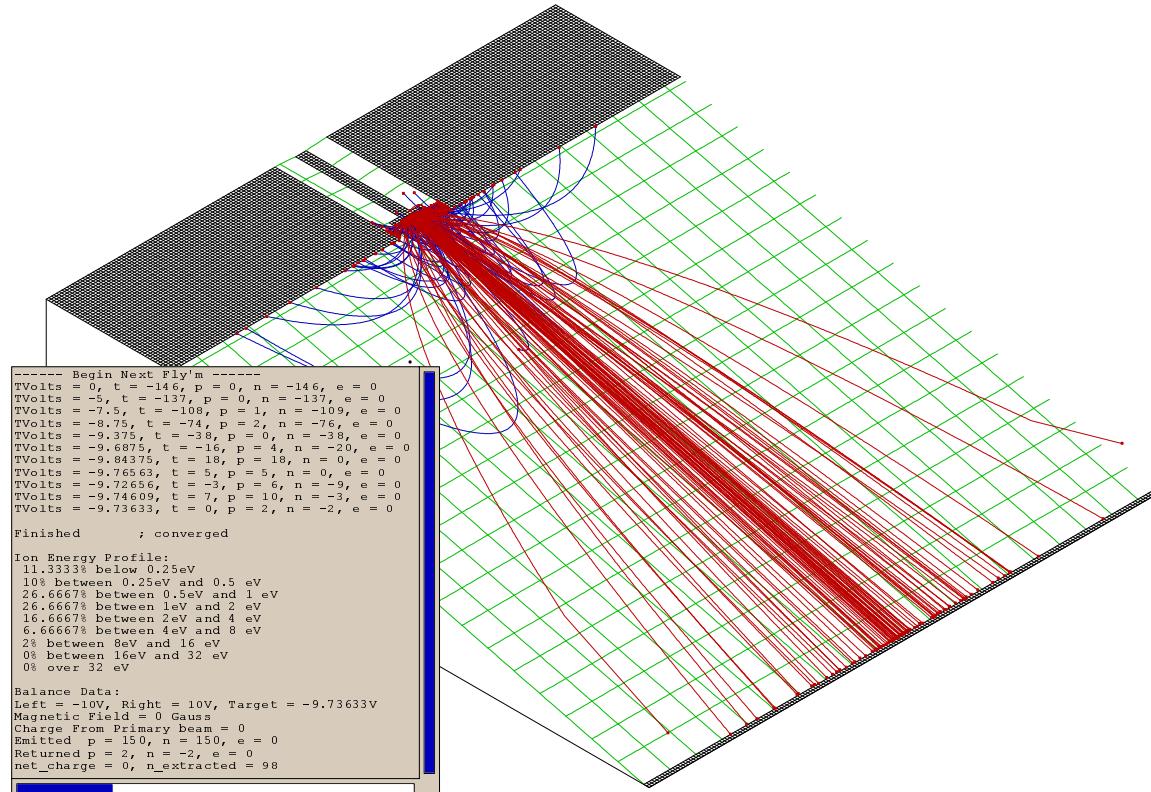
Controlling Successive Runs

- Strategy: Terminate and Initialize



Complex Multi-Run Simulations

- Monte Carlo -- Self-Charge Stabilization



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Afternoon User Programming Lab



- Self-directed lab. Do what interests you.
- Options:
 - Form groups to work on a common interest
 - Explore user program demos in reference
 - Continue to explore a previous lab
 - Attack the instructors

